

Examples (convex sets)

4) Euclidean balls

$$B(\bar{x}, r) = \{x \in \mathbb{R}^n : \|x - \bar{x}\|_2 \leq r\}$$

↑ ↑
Center radius



Verify its convexity:

Take $x, y \in B(\bar{x}, r)$; $\alpha \in [0, 1]$. Want: $\alpha x + (1-\alpha)y \in B(\bar{x}, r)$

We compute

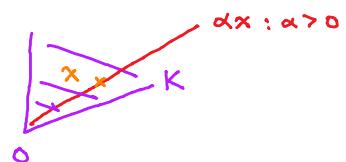
$$\begin{aligned} \|\alpha x + (1-\alpha)y - \bar{x}\|_2 &= \|\alpha(x - \bar{x}) + (1-\alpha)(y - \bar{x})\|_2 \\ &\leq \underbrace{\alpha\|x - \bar{x}\|_2}_{\leq r} + (1-\alpha)\underbrace{\|y - \bar{x}\|_2}_{\leq r} \quad (\text{triangle inequality}) \\ &\leq r, \end{aligned}$$

Generalization: $B_q(\bar{x}, r) = \{x \in \mathbb{R}^n : \|x - \bar{x}\|_q \leq r\}$ is convex
for any $q \geq 1$.

5) Convex cone

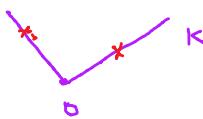
Definition: A set $K \subseteq \mathbb{R}^n$ is called a cone if

$$\forall x \in K, \alpha > 0 \cdot \alpha x \in K$$



Q: Must a cone be convex?

A: No. For instance:



Definition: A convex cone is a cone that is convex.

Examples: ① \mathbb{R}_+^n (trivial)

② $S_+^n = \{X \in S^n : X \succeq 0\}$ (Exercise)

Set of $n \times n$ real
Symmetric matrices

Convexity-Preserving Operations

Convexity - Preserving Operations

Motivation: So far, we prove convexity by first principles.

Q: Are there other ways?

Examples

① Let $S_1, S_2 \subseteq \mathbb{R}^n$ be convex sets.

• $S_1 \cup S_2$ convex? No. 

• $S_1 \cap S_2$ convex? Yes. (exercise)

② Affine Transformation

Definition: We say that $A: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is an affine map if

$$\forall x, y \in \mathbb{R}^n; \alpha \in \mathbb{R} : A(\underbrace{\alpha x + (1-\alpha)y}_{\text{affine combination of } x \text{ and } y}) = \alpha A(x) + (1-\alpha)A(y)$$

e.g. $\mathbb{R}^n \ni x \mapsto A(x) = c^T x + d \in \mathbb{R}$; $c \in \mathbb{R}^n, d \in \mathbb{R}$

Proposition: Let $A: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be an affine map, $S \subseteq \mathbb{R}^n$ be a convex set. Then, $A(S) \triangleq \{A(x) : x \in S\}$ is convex.

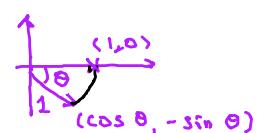
e.g.

① Translation: $A: \mathbb{R}^n \rightarrow \mathbb{R}^n : A(x) = x + d, d \in \mathbb{R}^n$ given

② Rotation: $A: \mathbb{R}^n \rightarrow \mathbb{R}^n : A(x) = Ux, U \in \mathbb{R}^{n \times n}$ orthogonal matrix $\hookrightarrow U^T U = UU^T = I$

e.g.: $n=2$

$$U = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$$

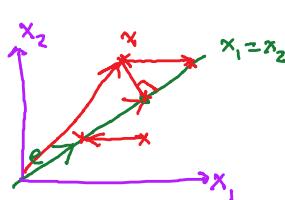


(clockwise rotation by θ)

③ Projection: $A: \mathbb{R}^n \rightarrow \mathbb{R}^m : A(x) = Px ; P$ projection matrix $\hookrightarrow P^2 = P$

$$\text{e.g. } P = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}$$

$$Px = \begin{bmatrix} x_2 \\ x_2 \end{bmatrix}$$



$$P' = \frac{1}{2}ee^T = \frac{1}{2} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

Note: P' is orthogonal projection.

Mathematically, P is an orthogonal projection if $P^2 = P$
and $P = P^T$

④ Ellipsoid

$$E(\bar{x}, Q) = \left\{ x \in \mathbb{R}^n : (x - \bar{x})^T Q (x - \bar{x}) \leq 1 \right\}$$

↑ ↗
Center axes

$$\bar{x} \in \mathbb{R}^n, \quad Q \succ 0$$

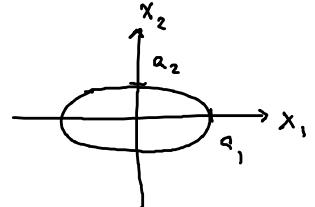
↑ positive definite

e.g.

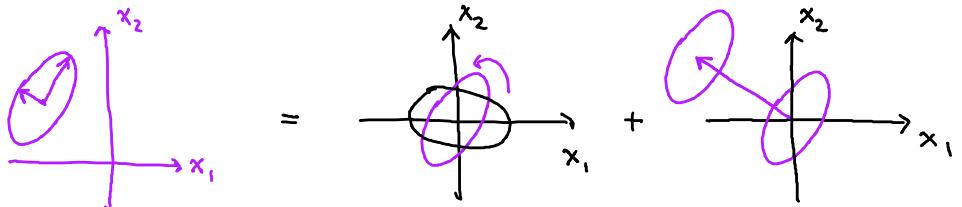
a) $Q = \frac{1}{r^2} I \Rightarrow E(\bar{x}, Q) = B(\bar{x}, r)$

b) $n=2$: $\frac{x_1^2}{a_1^2} + \frac{x_2^2}{a_2^2} \leq 1$

$$\Leftrightarrow \underbrace{\begin{bmatrix} x_1 & x_2 \end{bmatrix}}_{x^T} \underbrace{\begin{bmatrix} \frac{1}{a_1^2} & 0 \\ 0 & \frac{1}{a_2^2} \end{bmatrix}}_Q \underbrace{\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}}_x \leq 1$$



c)



Claim: There exists an affine map A s.t.

$$A(B(0,1)) = E(\bar{x}, Q)$$

It follows from the proposition that $E(\bar{x}, Q)$ is convex